



Homework 6  
 Due 5pm, Friday, June 3, 2022

**Problem 1:** Let  $\mathcal{X}$  be a nonempty set and let  $\Theta \subseteq \mathbb{R}^P$ . Let  $f(\cdot): \Theta \times \mathcal{X} \rightarrow \mathbb{R}$  be a neural network and use the notation  $f_\theta(x)$ . Assume  $\nabla_\theta f_\theta(x)$  is well defined for all  $\theta$  and  $x$  and is continuous both in  $\theta$  and  $x$ . Let  $\theta_0 \in \Theta$  and define  $h(\cdot): \Theta \times \mathcal{X} \rightarrow \mathbb{R}$  as

$$h_\theta(x) = f_{\theta_0}(x) + \langle \nabla_\theta f_{\theta_0}(x), \theta - \theta_0 \rangle_{\mathbb{R}^P}.$$

To clarify,  $\nabla_\theta f_{\theta_0}(x) = (\nabla_\theta f_\theta(x))|_{\theta=\theta_0}$ . So,  $h_\theta(x)$  is the linearization of  $f_\theta$  with respect to  $\theta$  about  $\theta_0$ . (Note,  $h_\theta(x)$  is linear in  $\theta$ , but nonlinear in  $x$ .) Define the PDK  $K: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$  as

$$K(x, x') = \langle \nabla_\theta f_{\theta_0}(x), \nabla_\theta f_{\theta_0}(x') \rangle_{\mathbb{R}^P}, \quad \forall x, x' \in \mathcal{X}.$$

Let  $X_1, \dots, X_N \in \mathcal{X}$ , and define  $G \in \mathbb{R}^{N \times N}$  as

$$G_{ij} = K(X_i, X_j), \quad \forall i, j \in \{1, \dots, N\}.$$

Assume  $G$  is strictly positive definite. Let

$$\Phi = \begin{bmatrix} (\nabla_\theta f_{\theta_0}(X_1))^\top \\ (\nabla_\theta f_{\theta_0}(X_2))^\top \\ \vdots \\ (\nabla_\theta f_{\theta_0}(X_N))^\top \end{bmatrix} \in \mathbb{R}^{N \times P}, \quad \Delta = \begin{bmatrix} f_\star(X_1) - f_{\theta_0}(X_1) \\ f_\star(X_2) - f_{\theta_0}(X_2) \\ \vdots \\ f_\star(X_N) - f_{\theta_0}(X_N) \end{bmatrix} \in \mathbb{R}^N.$$

Consider the regression problem

$$\underset{\theta \in \mathbb{R}^P}{\text{minimize}} \quad \sum_{i=1}^N (h_\theta(X_i) - f_\star(X_i))^2.$$

Show that

$$\theta_\star = \theta_0 + \Phi^\top G^{-1} \Delta$$

is an optimal solution and that

$$h_{\theta_\star}(x) = f_{\theta_0}(x) + \sum_{j=1}^N K(x, X_j) (G^{-1} \Delta)_j, \quad \forall x \in \mathcal{X}.$$

*Remark.*  $\theta_\star$  is not the unique solution, but it is the so-called “minimum-norm” solution.

*Remark.* This problem considers learning with  $h_\theta$ , the linearization of  $f_\theta$ , rather than the actual neural network  $f_\theta$ . Interestingly, the learned  $h_{\theta_\star}$  is identical to the prediction function obtained via the NTK theory, which characterizes the training  $f_\theta$  in the infinite-width limit. In fact,  $K$  is the neural tangent kernel of  $f_\theta$  at  $\theta = \theta_0$ .

**Problem 2:** *NTK of random feature learning.* Consider the 2-layer MLP

$$f_\theta(x) = \sum_{i=1}^M \frac{1}{\sqrt{M}} \theta_i \sigma(a_i^\top x + b_i),$$

where  $\sigma: \mathbb{R} \rightarrow \mathbb{R}$  is a continuous activation function,  $a_1, \dots, a_N \in \mathbb{R}^d$  and  $b_1, \dots, b_N \in \mathbb{R}$  are initialized as

$$(a_i)_j \sim \mathcal{N}(0, 1/d), \quad b_i \sim \mathcal{N}(0, 1)$$

and not trained, and  $\theta_1, \dots, \theta_M \in \mathbb{R}$  are trainable parameters. (So we assume  $f_\theta$  outputs a scalar.) Let  $P$  be a probability measure with finite support. Consider training through

$$\underset{\theta \in \mathbb{R}^M}{\text{minimize}} \quad R[f_\theta],$$

and assume the risk  $R: L^2(P) \rightarrow \mathbb{R}$  is Fréchet differentiable. Show that the gradient flow dynamics on the parameters

$$\frac{d\theta}{dt} = -\nabla_\theta R[f_\theta]$$

induces the dynamics

$$\frac{d}{dt} f_\theta = -L_\Theta[\partial_f R],$$

with

$$\Theta(x, x') = \frac{1}{M} \sum_{i=1}^M \sigma(a_i^\top x + b_i) \sigma(a_i^\top x' + b_i).$$

(Note,  $\Theta$  is time-independent.) Also show that

$$\Theta \rightarrow \tilde{\Sigma}^{(2)}$$

in probability as  $M \rightarrow \infty$  pointwise for inputs  $(x, x')$ , where

$$\Sigma^{(1)}(x, x') = \frac{1}{d} x^\top x' + 1.$$

and

$$\tilde{\Sigma}^{(2)}(x, x') = \mathbb{E}_{f \sim \mathcal{GP}(0, \Sigma^{(1)})} [\sigma(f(x)) \sigma(f(x'))]$$

*Clarification.* In the NNGP and NTK lectures, we used the variance parameters  $\sigma_A$  and  $\sigma_b$ . Here, we set  $\sigma_A = \sigma_b = 1$  for the sake of simplicity.

**Problem 3:** *NTK with standard parameterization.* Consider the depth-2 MLP

$$\begin{aligned} f_\theta(x) &= y_2 \\ y_2 &= z_2, & z_2 &= A_2 y_1 + b_2 \in \mathbb{R}^{n_2}, \\ y_1 &= \sigma(z_1), & z_1 &= A_1 x + b_1 \in \mathbb{R}^{n_1}, \end{aligned}$$

where  $x \in \mathbb{R}^{n_0}$ ,  $A_\ell \in \mathbb{R}^{n_\ell \times n_{\ell-1}}$ , and  $b_\ell \in \mathbb{R}^{n_\ell}$ . Initialize the weights with

$$(A_1)_{ij} \sim \mathcal{N}(0, 1/n_0), \quad (b_1)_i \sim \mathcal{N}(0, 1)$$

and

$$(A_2)_{ij} \sim \mathcal{N}(0, 1/n_1), \quad (b_2)_i \sim \mathcal{N}(0, 1).$$

Consider training through

$$\underset{\theta}{\text{minimize}} \quad R[f_\theta],$$

and assume the risk  $R: L^2(P) \rightarrow \mathbb{R}$  is Fréchet differentiable. For  $n_1 < \infty$ , the gradient flow dynamics

$$\frac{d\theta}{dt} = -\frac{1}{n_1} \nabla_\theta R[f_\theta]$$

induces the dynamics

$$\frac{d}{dt} f_\theta = -L_{\frac{1}{n_1} \Theta_t} [\partial_f R].$$

Find a formula for the NTK  $\Theta_t$  and show that

$$\frac{1}{n_1} \Theta_0 \rightarrow \tilde{\Sigma}^{(2)} \otimes I_{n_2}$$

in probability as  $n_1 \rightarrow \infty$  pointwise for inputs  $(x, x')$  at time  $t = 0$ , where  $\tilde{\Sigma}^{(2)}$  is as defined in Problem 2.

**Problem 4:** *Gluing Lemma.* Let  $\Theta \subseteq \mathbb{R}^d$  be nonempty. For any  $\rho_1, \rho_2 \in \mathcal{P}(\Theta)$ , define

$$\Pi(\rho_1, \rho_2) = \{\pi \in \mathcal{P}(\Theta \times \Theta) \mid \text{probability measures on } \Theta \times \Theta \text{ with marginals } \rho_1 \text{ and } \rho_2\}.$$

Let  $\lambda, \mu, \nu \in \mathcal{P}(\Theta)$  and  $\pi_{1,2} \in \Pi(\lambda, \mu)$  and  $\pi_{2,3} \in \Pi(\mu, \nu)$ . Define  $P_i: \Theta \times \Theta \times \Theta \rightarrow \Theta$  for  $i = 1, 2, 3$  as

$$P_1(\theta_1, \theta_2, \theta_3) = \theta_1, \quad P_2(\theta_1, \theta_2, \theta_3) = \theta_2, \quad P_3(\theta_1, \theta_2, \theta_3) = \theta_3.$$

Define  $P_{i,j}: \Theta \times \Theta \times \Theta \rightarrow \Theta \times \Theta$  with  $1 \leq i < j \leq 3$  as

$$P_{i,j}(\theta_1, \theta_2, \theta_3) = (\theta_i, \theta_j).$$

Show that there is a  $\pi_{1,2,3} \in \mathcal{P}(\Theta \times \Theta \times \Theta)$  such that

$$P_{1\#}\pi_{1,2,3} = \lambda, \quad P_{2\#}\pi_{1,2,3} = \mu, \quad P_{3\#}\pi_{1,2,3} = \nu$$

and

$$\pi_{1,2} = P_{1,2\#}\pi_{1,2,3}, \quad \pi_{2,3} = P_{2,3\#}\pi_{1,2,3}, \quad \pi_{1,3} := P_{1,3\#}\pi_{1,2,3} \in \Pi(\lambda, \nu).$$

*Hint.* Disintegrate  $\pi_{1,2}$  as

$$d\pi_{1,2}(\theta_1, \theta_2) = d\tilde{\mu}_{\theta_1}(\theta_2)d\lambda(\theta_1)$$

and  $\pi_{2,3}$  as

$$d\pi_{2,3}(\theta_2, \theta_3) = d\tilde{\nu}_{\theta_2}(\theta_3)d\mu(\theta_2).$$

Define  $\pi_{1,2,3}$  as

$$d\pi_{1,2,3} = d\tilde{\nu}_{\theta_2}(\theta_3)d\tilde{\mu}_{\theta_1}(\theta_2)d\lambda(\theta_1).$$

**Problem 5:** *Triangle inequality of the Wasserstein distance.* Let  $\Theta = \Phi \subseteq \mathbb{R}^d$  and  $p \in [1, \infty)$ . Show that

$$W_p(\lambda, \nu) \leq W_p(\lambda, \mu) + W_p(\mu, \nu), \quad \forall \lambda, \mu, \nu \in \mathcal{P}^p(\Theta).$$

*Hint.* Let  $\pi_{1,2}$  and  $\pi_{2,3}$  be feasible joint probability measures for the optimization problems defining  $W_p(\lambda, \mu)$  and  $W_p(\mu, \nu)$ . (Do not assume  $\pi_{1,2}$  and  $\pi_{2,3}$  are optimal, since we do not know whether the minima are attained.) Using Problem 4, glue  $\pi_{1,2}$  and  $\pi_{2,3}$  to get  $\pi_{1,2,3}$  and  $\pi_{1,3}$ . Finally, use the Minkowski inequality in  $L^p(\pi_{1,2,3})$ .

**Problem 6:** *Optimum of book shifting via duality.* Let  $\Theta = \Phi = \mathbb{R}$ ,  $c(\theta, \phi) = \|\theta - \phi\|$ , and

$$\mu = \frac{1}{N} \sum_{i=1}^N \delta_i, \quad \nu = \frac{1}{N} \sum_{i=1}^N \delta_{i+1}.$$

Show that  $W_1(\mu, \nu) \geq 1$  by finding a suitable feasible  $\varphi \in \mathcal{L}_1$  for the Kantorovich–Rubinstein dual

$$W_1(\mu, \nu) = \left( \begin{array}{l} \text{maximize} \\ \varphi \in \mathcal{C}_0(\Theta) \\ \text{subject to} \end{array} \int_{\mathbb{R}} \varphi(\theta) d\mu(\theta) - \int_{\mathbb{R}} \varphi(\phi) d\nu(\phi) \right).$$

**Problem 7:** Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be continuously differentiable. Let

$$\mathbb{R}_+^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_1 \geq 0, \dots, x_n \geq 0\}$$

be the nonnegative orthant in  $\mathbb{R}^n$ . Consider the optimization problem

$$\begin{aligned} & \underset{\theta \in \mathbb{R}^n}{\text{minimize}} && f(x) \\ & \text{subject to} && x \in \mathbb{R}_+^n \end{aligned}$$

and let  $x^* \in \mathbb{R}_+^n$  be an optimal solution. Show that

$$\frac{\partial f}{\partial x_i}(x^*) \geq 0, \quad \forall i = 1, \dots, n$$

and

$$\frac{\partial f}{\partial x_i}(x^*) = 0, \quad \forall i \text{ such that } x_i^* > 0.$$

**Problem 8:** Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  be continuously differentiable. Let

$$\Delta^n = \{(x_1, \dots, x_n) \in \mathbb{R}^n \mid x_1 + \dots + x_n = 1, x_1 \geq 0, \dots, x_n \geq 0\}$$

be the probability simplex in  $\mathbb{R}^n$ . Consider the optimization problem

$$\begin{aligned} & \underset{\theta \in \mathbb{R}^n}{\text{minimize}} && f(x) \\ & \text{subject to} && x \in \Delta^n \end{aligned}$$

and let  $x^* \in \Delta^n$  be an optimal solution. Let

$$c = \min_{i=1, \dots, n} \frac{\partial f}{\partial x_i}(x^*).$$

Show that

$$\frac{\partial f}{\partial x_i}(x^*) = c, \quad \forall i \text{ such that } x_i^* > 0.$$

**Problem 9:** Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  and  $k > 0$ . Assume  $f$  is nonnegative homogeneous of degree  $k$ , i.e.,

$$f(\alpha x) = \alpha^k f(x), \quad \forall \alpha \geq 0, x \in \mathbb{R}^n.$$

Assume  $f$  is differentiable at  $x_0$ . Show that (i)

$$\langle x_0, \nabla f(x_0) \rangle = k f(x_0)$$

(ii) and

$$\nabla f(\alpha x_0) = \alpha^{k-1} \nabla f(x_0), \quad \forall \alpha > 0.$$

*Hint.* For (i), differentiate both sides of  $f(\alpha x_0) = \alpha^k f(x_0)$  with respect to  $\alpha$  and plug in  $\alpha = 1$ . For (ii), differentiate both sides of  $f(\alpha(x_0 + te_i)) = \alpha^k f(x_0 + te_i)$  with respect to  $t$  and plug in  $t = 0$ .

**Problem 10:** Let  $\sigma: \mathbb{R} \rightarrow \mathbb{R}$  defined as

$$\sigma(r) = \max\{r, 0\}$$

be the ReLU activation function. Of course,  $\sigma$  is nonnegative homogeneous of degree 1. Let  $x \in \mathbb{R}^d$  and  $\theta = (u, a, b) \in \mathbb{R} \times \mathbb{R}^d \times \mathbb{R}$ . Define

$$f(\theta) = u\sigma(a^\top x + b).$$

Show that (i)  $f(\theta)$  is nonnegative homogeneous of degree 2 and (ii)  $f(\theta)$ , is differentiable for (Lebesgue) almost all  $\theta \in \mathbb{R} \times \mathbb{R}^d \times \mathbb{R}$ .

*Clarification.* We view  $x$  as a fixed input.