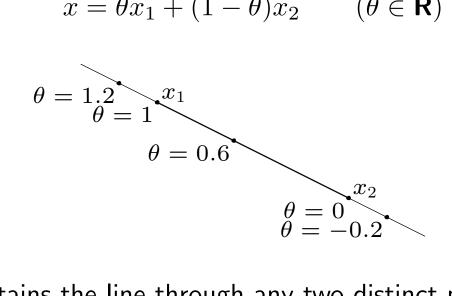
### 2. Convex sets

- affine and convex sets
- some important examples
- operations that preserve convexity
- generalized inequalities
- separating and supporting hyperplanes
- dual cones and generalized inequalities

#### Affine set

**line** through  $x_1$ ,  $x_2$ : all points

$$x = \theta x_1 + (1 - \theta) x_2 \qquad (\theta \in \mathbf{R})$$



**affine set**: contains the line through any two distinct points in the set

**example**: solution set of linear equations  $\{x \mid Ax = b\}$ 

(conversely, every affine set can be expressed as solution set of system of linear equations)

### **Convex set**

line segment between  $x_1$  and  $x_2$ : all points

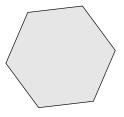
$$x = \theta x_1 + (1 - \theta)x_2$$

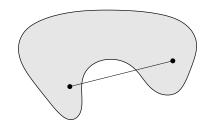
with  $0 \le \theta \le 1$ 

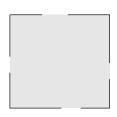
convex set: contains line segment between any two points in the set

$$x_1, x_2 \in C, \quad 0 \le \theta \le 1 \quad \Longrightarrow \quad \theta x_1 + (1 - \theta)x_2 \in C$$

examples (one convex, two nonconvex sets)







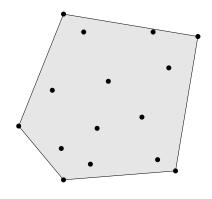
### Convex combination and convex hull

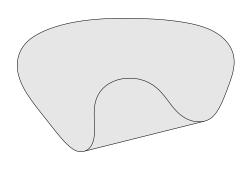
convex combination of  $x_1, \ldots, x_k$ : any point x of the form

$$x = \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k$$

with 
$$\theta_1 + \cdots + \theta_k = 1$$
,  $\theta_i \ge 0$ 

**convex hull conv** S: set of all convex combinations of points in S



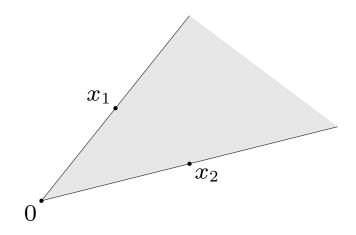


### Convex cone

conic (nonnegative) combination of  $x_1$  and  $x_2$ : any point of the form

$$x = \theta_1 x_1 + \theta_2 x_2$$

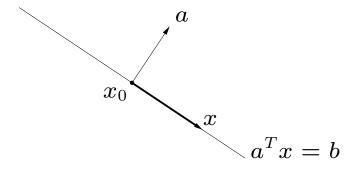
with  $\theta_1 \ge 0$ ,  $\theta_2 \ge 0$ 



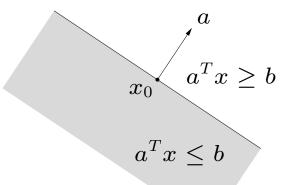
convex cone: set that contains all conic combinations of points in the set

# Hyperplanes and halfspaces

**hyperplane**: set of the form  $\{x \mid a^T x = b\}$   $(a \neq 0)$ 



**halfspace:** set of the form  $\{x \mid a^T x \leq b\}$   $(a \neq 0)$ 



- a is the normal vector
- hyperplanes are affine and convex; halfspaces are convex

### **Euclidean balls and ellipsoids**

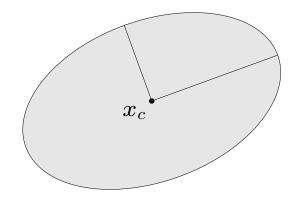
(Euclidean) ball with center  $x_c$  and radius r:

$$B(x_c, r) = \{x \mid ||x - x_c||_2 \le r\} = \{x_c + ru \mid ||u||_2 \le 1\}$$

ellipsoid: set of the form

$$\{x \mid (x - x_c)^T P^{-1} (x - x_c) \le 1\}$$

with  $P \in \mathbf{S}_{++}^n$  (i.e., P symmetric positive definite)



other representation:  $\{x_c + Au \mid ||u||_2 \le 1\}$  with A square and nonsingular

#### Norm balls and norm cones

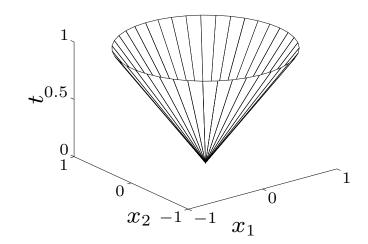
**norm:** a function  $\|\cdot\|$  that satisfies

- $||x|| \ge 0$ ; ||x|| = 0 if and only if x = 0
- ||tx|| = |t| ||x|| for  $t \in \mathbf{R}$
- $||x + y|| \le ||x|| + ||y||$

notation:  $\|\cdot\|$  is general (unspecified) norm;  $\|\cdot\|_{\text{symb}}$  is particular norm **norm ball** with center  $x_c$  and radius r:  $\{x\mid \|x-x_c\|\leq r\}$ 

norm cone:  $\{(x,t) \mid ||x|| \le t\}$ 

Euclidean norm cone is called secondorder cone



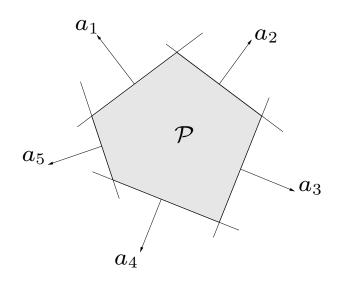
norm balls and cones are convex

# **Polyhedra**

solution set of finitely many linear inequalities and equalities

$$Ax \leq b, \qquad Cx = d$$

 $(A \in \mathbf{R}^{m \times n}, C \in \mathbf{R}^{p \times n}, \leq \text{is componentwise inequality})$ 



polyhedron is intersection of finite number of halfspaces and hyperplanes

### Positive semidefinite cone

#### notation:

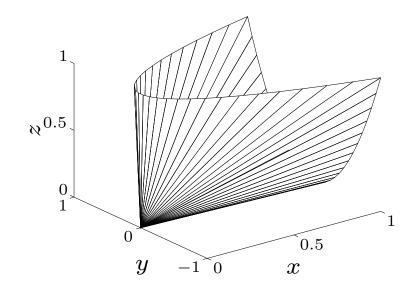
- $S^n$  is set of symmetric  $n \times n$  matrices
- $\mathbf{S}_{+}^{n} = \{X \in \mathbf{S}^{n} \mid X \succeq 0\}$ : positive semidefinite  $n \times n$  matrices

$$X \in \mathbf{S}^n_+ \iff z^T X z \ge 0 \text{ for all } z$$

 $\mathbf{S}^n_+$  is a convex cone

•  $\mathbf{S}_{++}^n = \{X \in \mathbf{S}^n \mid X \succ 0\}$ : positive definite  $n \times n$  matrices

example:  $\begin{bmatrix} x & y \\ y & z \end{bmatrix} \in \mathbf{S}_{+}^{2}$ 



# Operations that preserve convexity

practical methods for establishing convexity of a set C

1. apply definition

$$x_1, x_2 \in C, \quad 0 \le \theta \le 1 \quad \Longrightarrow \quad \theta x_1 + (1 - \theta) x_2 \in C$$

- 2. show that C is obtained from simple convex sets (hyperplanes, halfspaces, norm balls, . . . ) by operations that preserve convexity
  - intersection
  - affine functions
  - perspective function
  - linear-fractional functions

### Intersection

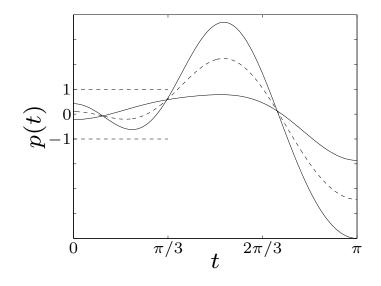
the intersection of (any number of) convex sets is convex

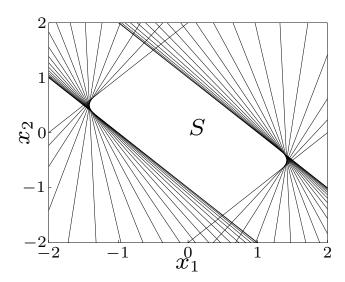
### example:

$$S = \{x \in \mathbf{R}^m \mid |p(t)| \le 1 \text{ for } |t| \le \pi/3\}$$

where  $p(t) = x_1 \cos t + x_2 \cos 2t + \dots + x_m \cos mt$ 

for m=2:





### **Affine function**

suppose  $f: \mathbf{R}^n \to \mathbf{R}^m$  is affine  $(f(x) = Ax + b \text{ with } A \in \mathbf{R}^{m \times n}, b \in \mathbf{R}^m)$ 

ullet the image of a convex set under f is convex

$$S \subseteq \mathbf{R}^n \text{ convex} \implies f(S) = \{f(x) \mid x \in S\} \text{ convex}$$

ullet the inverse image  $f^{-1}(C)$  of a convex set under f is convex

$$C \subseteq \mathbf{R}^m \text{ convex} \implies f^{-1}(C) = \{x \in \mathbf{R}^n \mid f(x) \in C\} \text{ convex}$$

#### examples

- scaling, translation, projection
- solution set of linear matrix inequality  $\{x \mid x_1A_1 + \cdots + x_mA_m \leq B\}$  (with  $A_i, B \in \mathbf{S}^p$ )
- hyperbolic cone  $\{x \mid x^T P x \leq (c^T x)^2, c^T x \geq 0\}$  (with  $P \in \mathbf{S}^n_+$ )

### Perspective and linear-fractional function

perspective function  $P: \mathbb{R}^{n+1} \to \mathbb{R}^n$ :

$$P(x,t) = x/t,$$
 dom  $P = \{(x,t) \mid t > 0\}$ 

images and inverse images of convex sets under perspective are convex

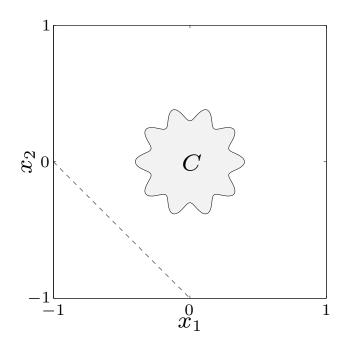
linear-fractional function  $f: \mathbb{R}^n \to \mathbb{R}^m$ :

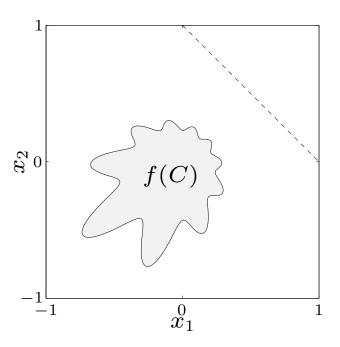
$$f(x) = \frac{Ax + b}{c^T x + d},$$
  $\mathbf{dom} f = \{x \mid c^T x + d > 0\}$ 

images and inverse images of convex sets under linear-fractional functions are convex

### **example** of a linear-fractional function

$$f(x) = \frac{1}{x_1 + x_2 + 1}x$$





# **Generalized inequalities**

a convex cone  $K \subseteq \mathbf{R}^n$  is a **proper cone** if

- K is closed (contains its boundary)
- *K* is solid (has nonempty interior)
- *K* is pointed (contains no line)

#### examples

- nonnegative orthant  $K = \mathbf{R}^n_+ = \{x \in \mathbf{R}^n \mid x_i \ge 0, i = 1, \dots, n\}$
- positive semidefinite cone  $K = \mathbf{S}_{+}^{n}$
- nonnegative polynomials on [0,1]:

$$K = \{x \in \mathbf{R}^n \mid x_1 + x_2t + x_3t^2 + \dots + x_nt^{n-1} \ge 0 \text{ for } t \in [0, 1]\}$$

**generalized inequality** defined by a proper cone K:

$$x \leq_K y \iff y - x \in K, \qquad x \prec_K y \iff y - x \in \mathbf{int} K$$

#### examples

• componentwise inequality  $(K = \mathbf{R}_{+}^{n})$ 

$$x \preceq_{\mathbf{R}^n_+} y \iff x_i \leq y_i, \quad i = 1, \dots, n$$

• matrix inequality  $(K = \mathbf{S}_{+}^{n})$ 

$$X \preceq_{\mathbf{S}^n_{\perp}} Y \iff Y - X$$
 positive semidefinite

these two types are so common that we drop the subscript in  $\leq_K$  properties: many properties of  $\leq_K$  are similar to  $\leq$  on  $\mathbf{R}$ , e.g.,

$$x \leq_K y, \quad u \leq_K v \implies x + u \leq_K y + v$$

#### Minimum and minimal elements

 $\preceq_K$  is not in general a *linear ordering*: we can have  $x \npreceq_K y$  and  $y \npreceq_K x$   $x \in S$  is **the minimum element** of S with respect to  $\preceq_K$  if

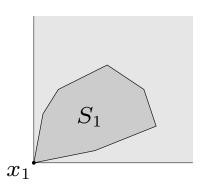
$$y \in S \implies x \leq_K y$$

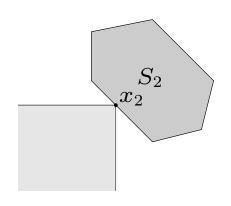
 $x \in S$  is a minimal element of S with respect to  $\leq_K$  if

$$y \in S$$
,  $y \leq_K x \implies y = x$ 

example  $(K = \mathbf{R}_+^2)$ 

 $x_1$  is the minimum element of  $S_1$   $x_2$  is a minimal element of  $S_2$ 

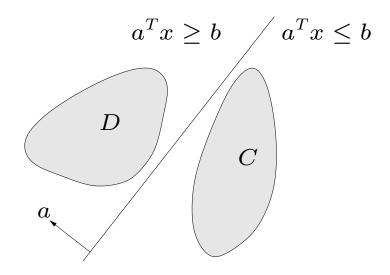




# Separating hyperplane theorem

if C and D are nonempty disjoint convex sets, there exist  $a \neq 0$ , b s.t.

$$a^T x \le b \text{ for } x \in C, \qquad a^T x \ge b \text{ for } x \in D$$



the hyperplane  $\{x \mid a^Tx = b\}$  separates C and D

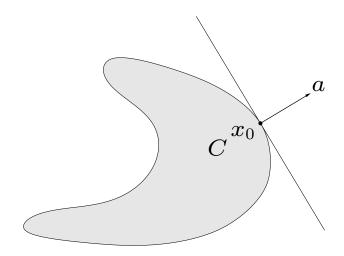
strict separation requires additional assumptions (e.g., C is closed, D is a singleton)

# **Supporting hyperplane theorem**

**supporting hyperplane** to set C at boundary point  $x_0$ :

$$\{x \mid a^T x = a^T x_0\}$$

where  $a \neq 0$  and  $a^T x \leq a^T x_0$  for all  $x \in C$ 



supporting hyperplane theorem: if C is convex, then there exists a supporting hyperplane at every boundary point of C

# Dual cones and generalized inequalities

**dual cone** of a cone K:

$$K^* = \{ y \mid y^T x \ge 0 \text{ for all } x \in K \}$$

examples

- $\bullet \ K = \mathbf{R}^n_+ : \ K^* = \mathbf{R}^n_+$
- $K = \mathbf{S}_{+}^{n}$ :  $K^{*} = \mathbf{S}_{+}^{n}$
- $K = \{(x,t) \mid ||x||_2 \le t\}$ :  $K^* = \{(x,t) \mid ||x||_2 \le t\}$
- $K = \{(x,t) \mid ||x||_1 \le t\}$ :  $K^* = \{(x,t) \mid ||x||_\infty \le t\}$

first three examples are **self-dual** cones

dual cones of proper cones are proper, hence define generalized inequalities:

$$y \succeq_{K^*} 0 \iff y^T x \ge 0 \text{ for all } x \succeq_K 0$$